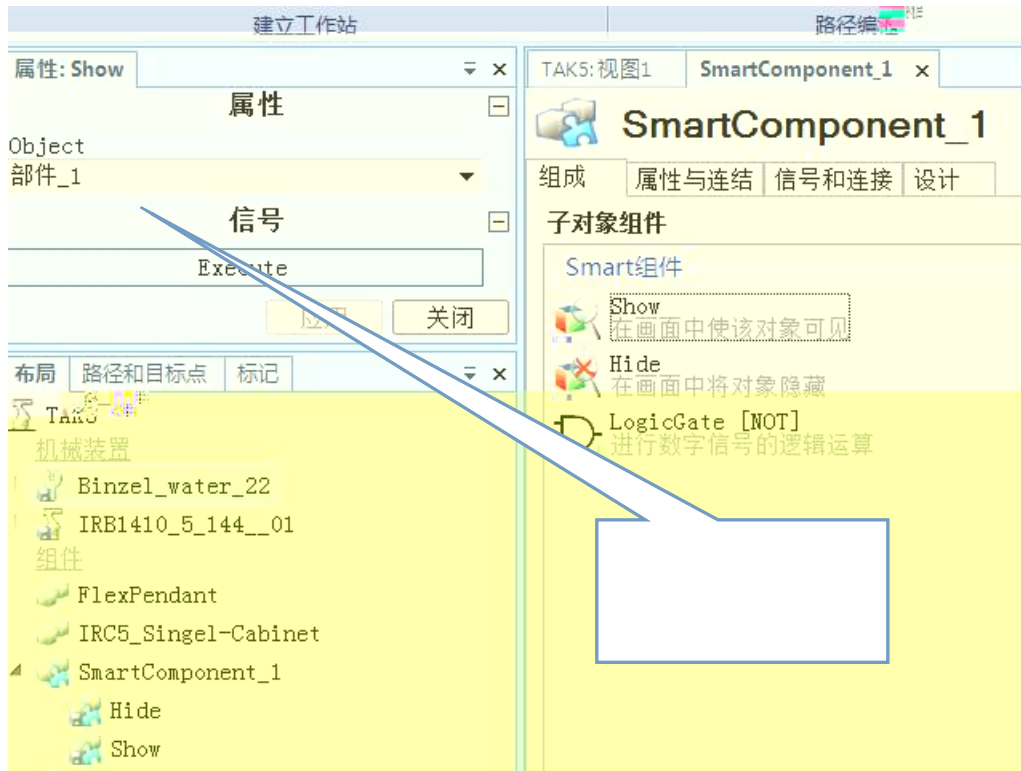
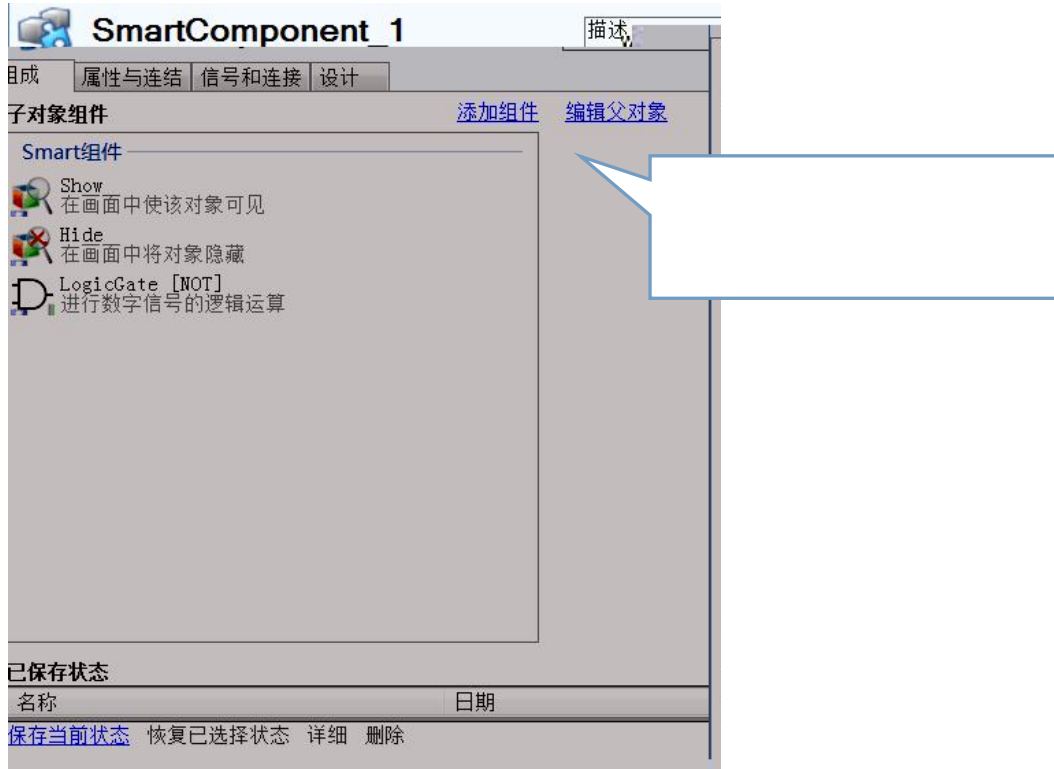
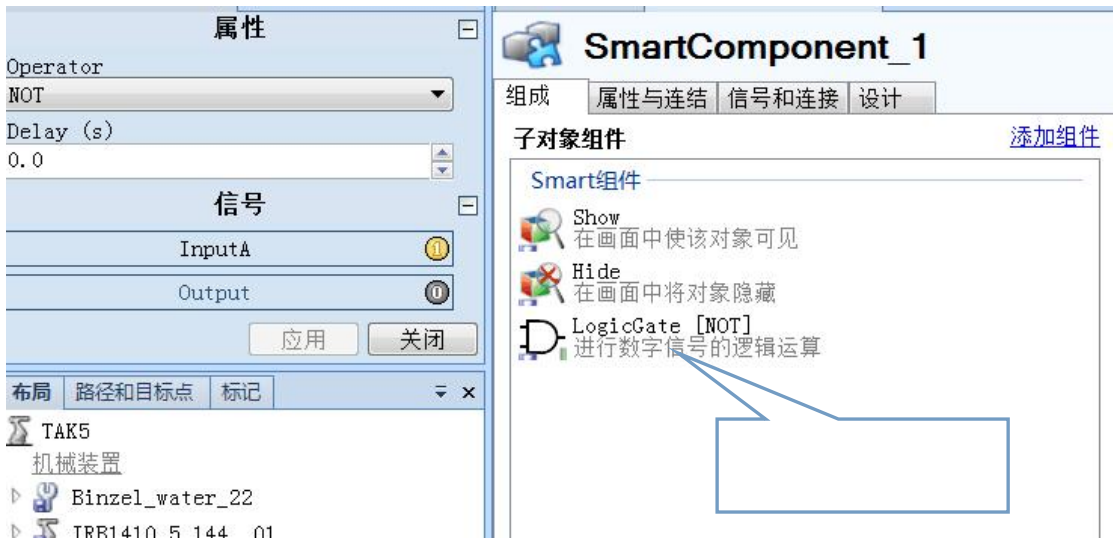
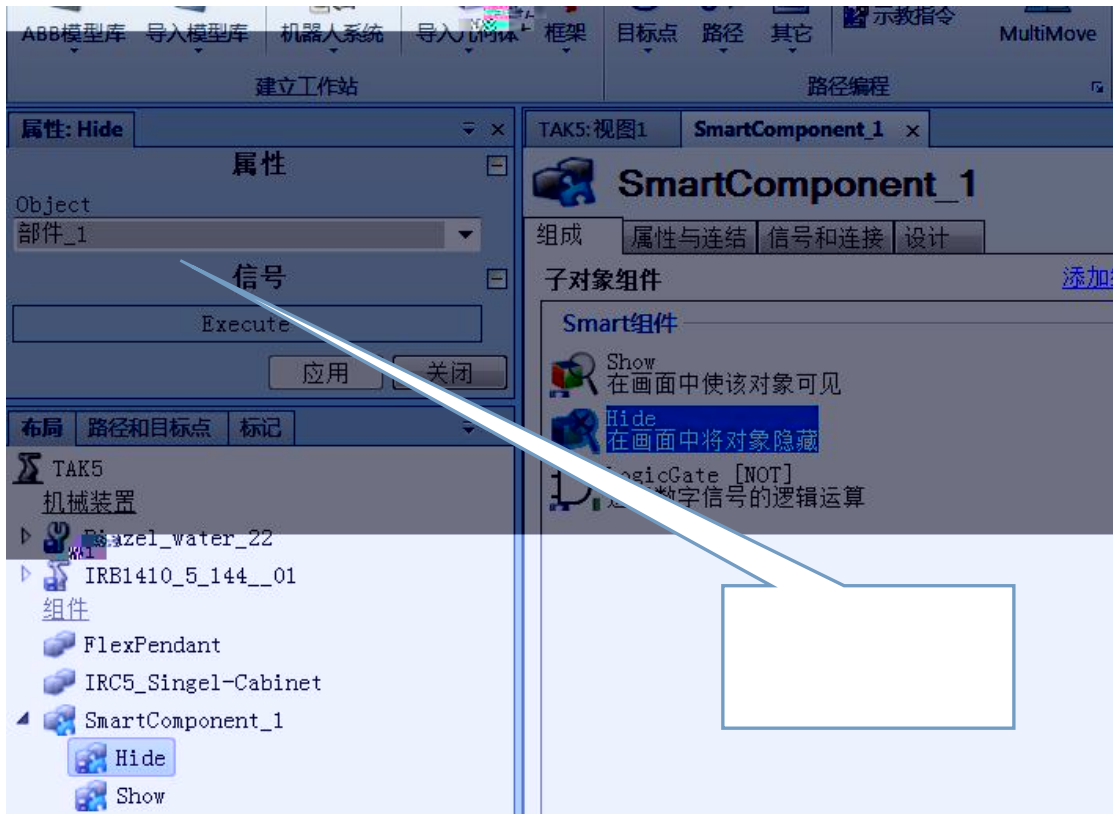
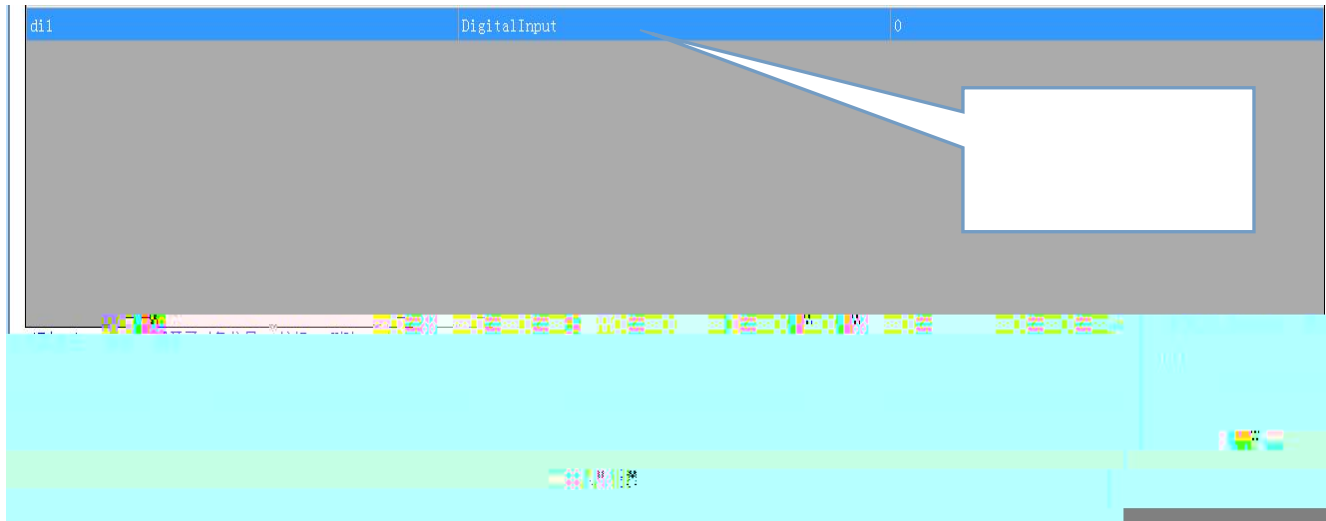


Smart







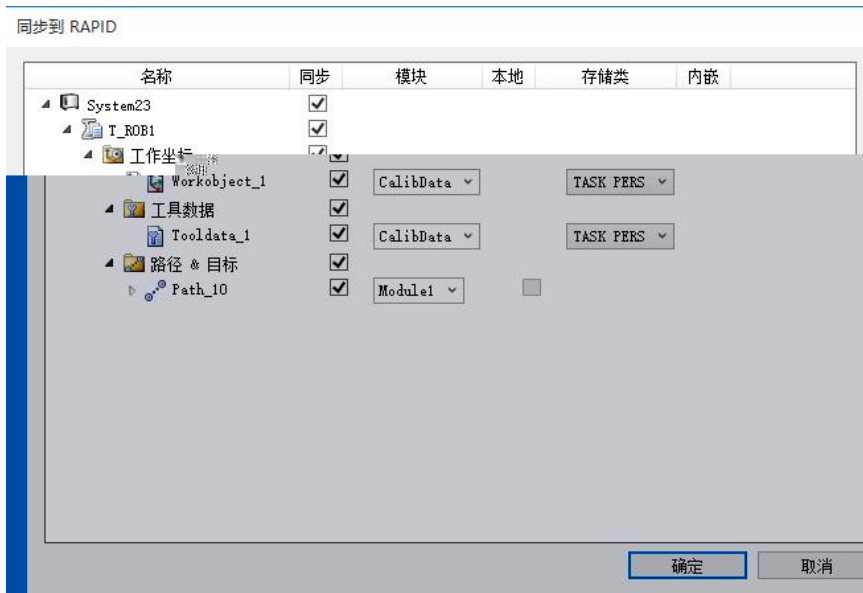
IO

实例编辑器

名称	值	信息
Name	do1	
Type of Signal	Digital Output ▾	
Assigned to Device	▾	
Signal Identification Label		
Category		
Access Level	Default ▾	
Default Value	0	
Safe Level	DefaultSafeLevel ▾	



MoveJ ▾ * v1000 ▾ z1 ▾ tWeldGun ▾ \WObj:=Workobject_1 ▾ 选择方式 ▾



TAKS:视图1 仿真设定 x 70% 43.4K 953K

活动仿真场景: (SimulationConfiguration) - T4 添加... 删除 重命名

场景设置

初始状态: [] 管理状态

仿真对象:

物体	仿真
TAK5	
Controllers	
System3	<input checked="" type="checkbox"/>
T_ROB1	<input checked="" type="checkbox"/>
Smart_Components	
SmartComponent_1	<input checked="" type="checkbox"/>

System3 的设置

当仿真开始时自动开始所选任务的执行。

运行模式

单个周期

连续

初始状态

State Name: 1
Description:
Date: 2016/1/6 8:37:58

Controller States

System3:

Variable values:

```
/RAPID/T_ROB1/BASE/load0 = [0.001,0.0,0.001],[1,0.0,0]0.0,0.0]
/RAPID/T_ROB1/BASE/wobj0 = [FALSE,TRUE,"",[0.0,0],[1,0.0,0],[0.0,0],[1,0.0,0]]
/RAPID/T_ROB1/BASE/tool0 = [TRUE,[0.0,0],[1,0.0,0],[0.001,[0.0,0.001],[1,0.0,0],0.0,0.0]]
/RAPID/T_ROB1/CaltData/WeldGun = [S,"",[0.0,0],[1,0.0,0],[0.0,0],[1,0.0,0]]
/RAPID/T_ROB1/ContData/Werkobjct_1 = [FALSE,TRUE,"",[0.0,0],[1,0.0,0],[0.0,0],[1,0.0,0]]
```

I/O Signal values

```
do1 = 0
do2 = 0
```

虚拟时间模式: 时间段 自由运行